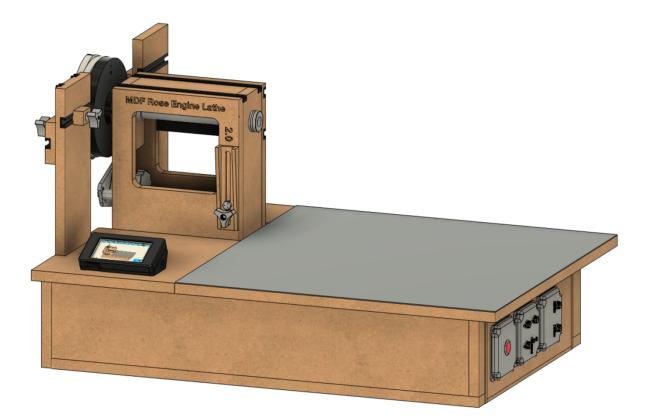
MDF Rose Engine Lathe 2.0 with Stepper Motor Drive



Instructions for Building Control System for Multiple Stepper Motors

Part 2 – MDF Case

Version 4.0 09 June 2022

MDF Rose Engine Lathe 2.0 Build Instructions – Control System for Multiple Stepper Motors

Permission is not granted to manufacture these for sale.

MDF Rose Engine Lathe 2.0 Build Instructions – Control System for Multiple Stepper Motors Table of Contents

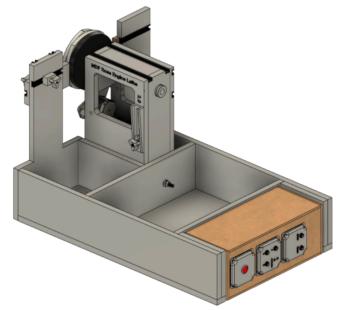
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Build Instructions – Control System for Multiple Stepper Motors

Some have chosen to put the stepper motor controls in the lathe's carcass, under the bed of the lathe. However, placing all the pieces together in a separate box gives these benefits:

- 1. This controls box is designed be placed under the bed in the MDF Rose Engine Lathe 2.0 (as shown in the picture to the right {the bed cover is removed}).
- 2. This approach also allows for the controls box to be used with the original MDF Rose Engine Lathe, just placing the box somewhere near the lathe.
- 3. This also frees up space under the bed for:
 - a. Storage of parts or tools, or
 - b. Making a gap-bed lathe.
- 4. The many connections between the various pieces inside the box are already in place and the user does not have to figure out the correct alignment of connectors when building the MDF Rose Engine Lathe.

The details for how we are building the one you can buy are below. These are documented for our use to ensure consistency, and we are publishing them for anyone who wishes to build their own.



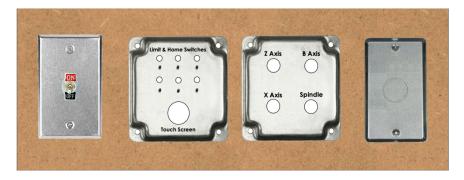
MDF Rose Engine Lathe 2.0 (B1 and B1A removed)

The sequence of activities follows the layout of this document. That was done consciously. Changes to the sequence should be considered strongly before making changes.

Build Instructions – Control System for Multiple Stepper Motors

Options for the Controls Box Enclosure

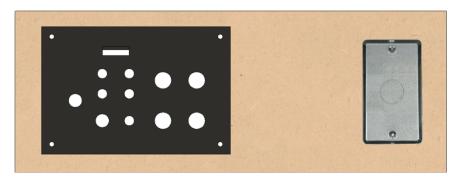
There are two options for building this box.



Option 1 – Original Design

• Uses off-the-shelf switch plates

If you choose this option, continue on page 16.



Option 2 – 3D-printed Panel

• Black panel is 3D printed.

This panel design is available on the MDF Rose Engine Lathe 2.0 Library in the book titled, <u>3D Printed Parts</u>. Open the section titled, "Control System for Multiple Stepper Motors".

Use version 2 or 3, depending on the type of limit switch jacks you are using.

If you choose this option, continue on page 16.

Build Instructions – Control System for Multiple Stepper Motors

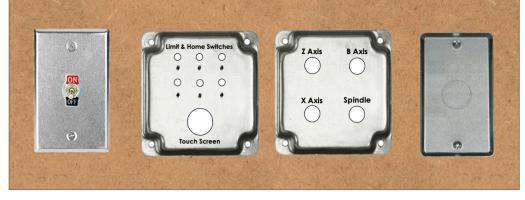
Section 1, Option 1 – Controls Box Enclosure

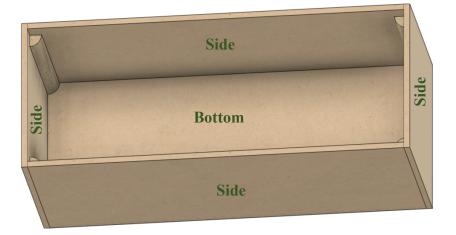
- 1. A top and bottom made from ³/₄" MDF,
- 2. Four sides made from ¹/₄" MDF, and
- 3. 4 corner posts made from quarter-round trim (these are recommended but not required. The box can be assembled without them).

The quarter-rounds are used to give the top and bottom something to set the spacing correctly.

The four ¹/4" thick sides are screwed to the ³/4" MDF used for the top and bottom.

Replacing the top, and removing the sides reveals the view to the left.



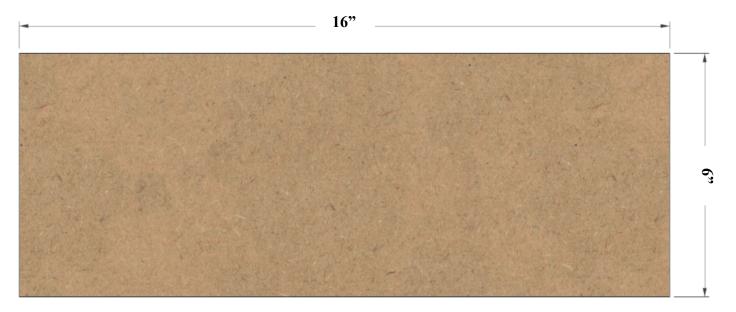


Build Instructions – Control System for Multiple Stepper Motors

Before Assembly The following instructions should be followed before assembling the controls box

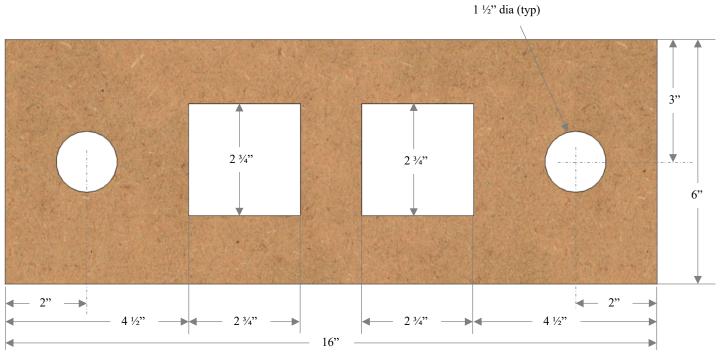
Bottom

This is made from ³/₄" MDF.



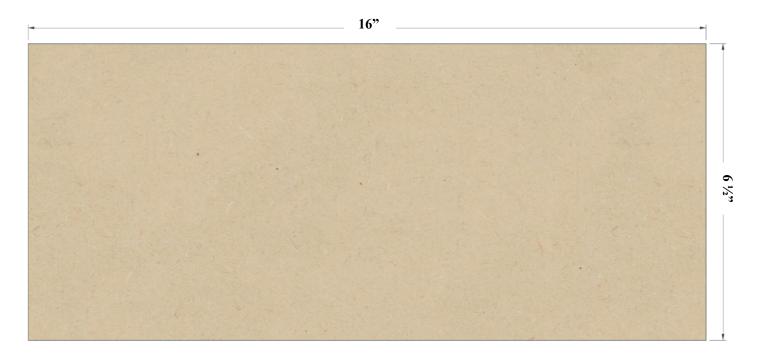
MDF Rose Engine Lathe 2.0 Build Instructions – Control System for Multiple Stepper Motors

<u>Top</u> This is made from ³/₄" MDF.



Build Instructions – Control System for Multiple Stepper Motors

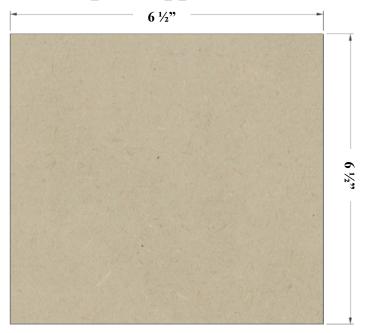
Long Sides (2) There are two of these, and they are made from ¹/4" MDF.



Build Instructions – Control System for Multiple Stepper Motors

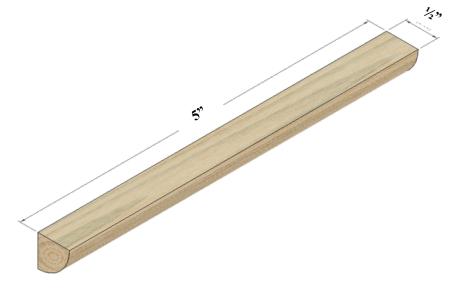
Short Sides (2)

There are two of these, and they are made from ¹/₄" MDF.



Quarter Rounds (4)

There are four of these, and they are made from any good trim material. These are ¹/₂" radius, but that is not terribly critical.



Build Instructions – Control System for Multiple Stepper Motors

Assembly

Glue the four quarter rounds to the ends of the two long sides. Be certain to:

- 1. center the quarter round so there is ³/₄" on each end, and
- 2. ensure the edges are flush to each other.



Build Instructions – Control System for Multiple Stepper Motors

Electrical Plates for Connectors

Power Infeed

Use a 1-gang plate with the hole punched out for the cable strain relief. Secure the power cable in place using the 3/8 in. Twin-Screw Cable Clamp Connector. Wait until later to tighten the screws holding the power cable into place.





Power Switch

Use a 1-gang plate which is blank. Drill a ¹/2" hole in the center and secure the power switch to it.



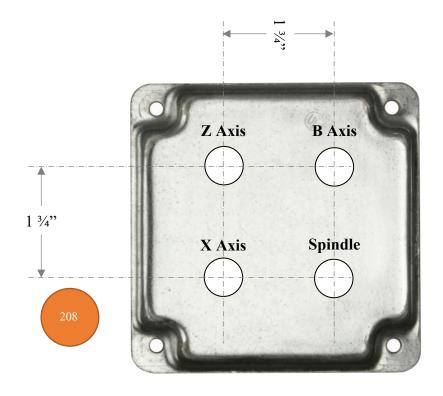


Build Instructions – Control System for Multiple Stepper Motors

Stepper Motor Jacks Use a 2-gang plate which is blank. Drill 4 holes which are each 5/8 diameter.

Label these as:

- Z Axis •
- **B** Axis
- X Axis
- Spindle ٠



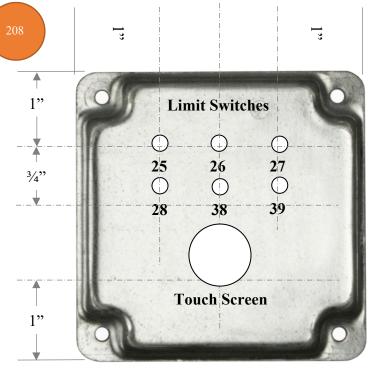
Build Instructions – Control System for Multiple Stepper Motors

Other Jacks

Use a 2-gang plate which is blank.

Drill 6 holes which are each 6mm or ${}^{15}/{}_{64}$ " diameter. Label these as:

Limit Switches			
25	26	27	
28	38	39	



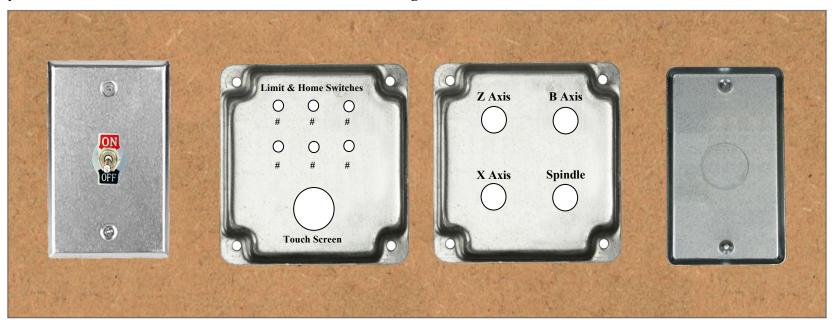
For the touch screen (the Nextion touch screen), the recommended approach is to use a connector like a GX-12/4 (#215) to connect the wires. For that connector, drill the hole using a 12mm bit. Center it left to right and 1" from the outer edge. Label this as:

Touch Screen

Build Instructions – Control System for Multiple Stepper Motors

Mounting the Covers

The layout below is recommended. This minimizes cable management issues when used.



NOTE: Screw these plates into place using 5/8" #6, flat head, particle board screws (item #408 in the bill of materials).

408

Continue on to Section 2, starting on pg. 34.

Build Instructions – Control System for Multiple Stepper Motors

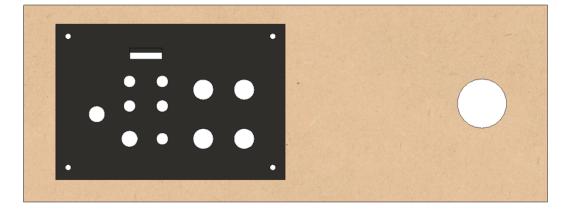
Section 1, Option 2 – Controls Box Enclosure

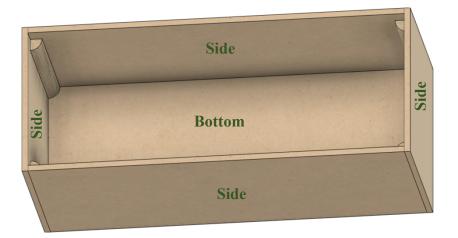
- 1. A top and bottom made from ³/₄" MDF,
- 2. Four sides made from ¹/₄" MDF, and
- 3. 4 corner posts made from quarter-round trim (these are recommended but not required. The box can be assembled without them).

The quarter-rounds are used to give the top and bottom something to set the spacing correctly.

The four $\frac{1}{4}$ " thick sides are screwed to the $\frac{3}{4}$ " MDF used for the top and bottom.

Replacing the top, and removing the sides reveals the view to the left.





Build Instructions – Control System for Multiple Stepper Motors

Before Assembly The following instructions should be followed before assembling the controls box

Bottom

This is made from ³/₄" MDF.

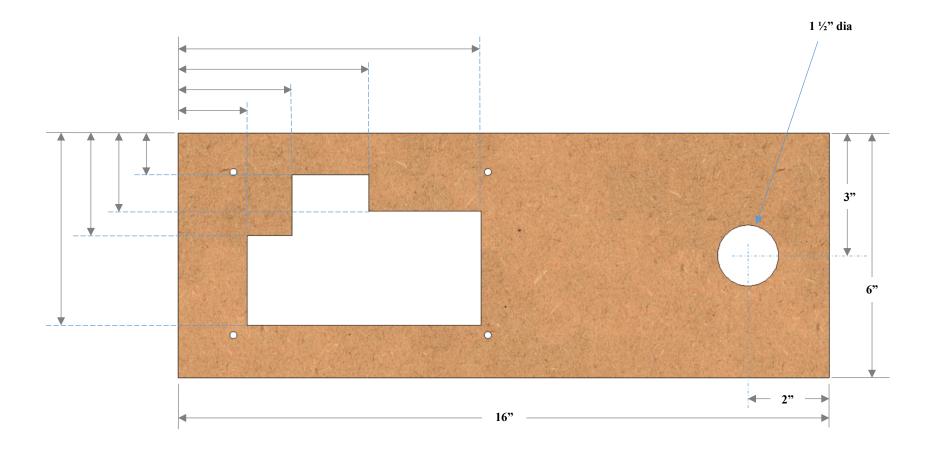


Build Instructions – Control System for Multiple Stepper Motors

<u>Top</u>

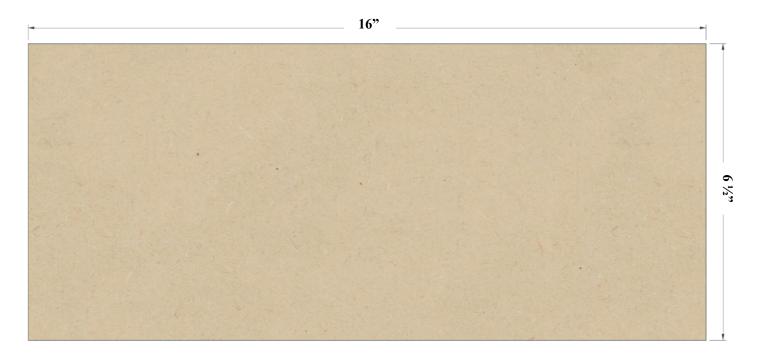
This is made from ³/₄" MDF. This layout is for the version 2 or version 3 plate in the book titled, <u>3D Printed Parts</u>. If you use version 1, modify the layout as necessary.

For the 3D-printed plate's mounting holes, it is best to drill them based on the plate's position after cutting the opening. Do be sure it is properly aligned before drilling the holes.



Build Instructions – Control System for Multiple Stepper Motors

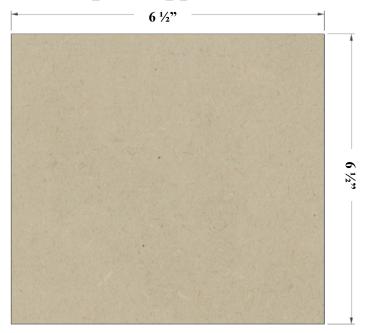
Long Sides (2) There are two of these, and they are made from ¹/4" MDF.



Build Instructions – Control System for Multiple Stepper Motors

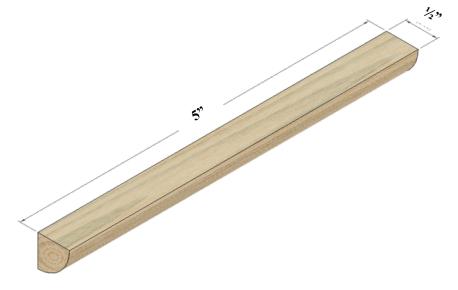
Short Sides (2)

There are two of these, and they are made from ¹/₄" MDF.



Quarter Rounds (4)

There are four of these, and they are made from any good trim material. These are ¹/₂" radius, but that is not terribly critical.



Build Instructions – Control System for Multiple Stepper Motors

Assembly

Glue the four quarter rounds to the ends of the two long sides. Be certain to:

- center the quarter round so there is ³/₄" on each end, and
 ensure the edges are flush to each other.

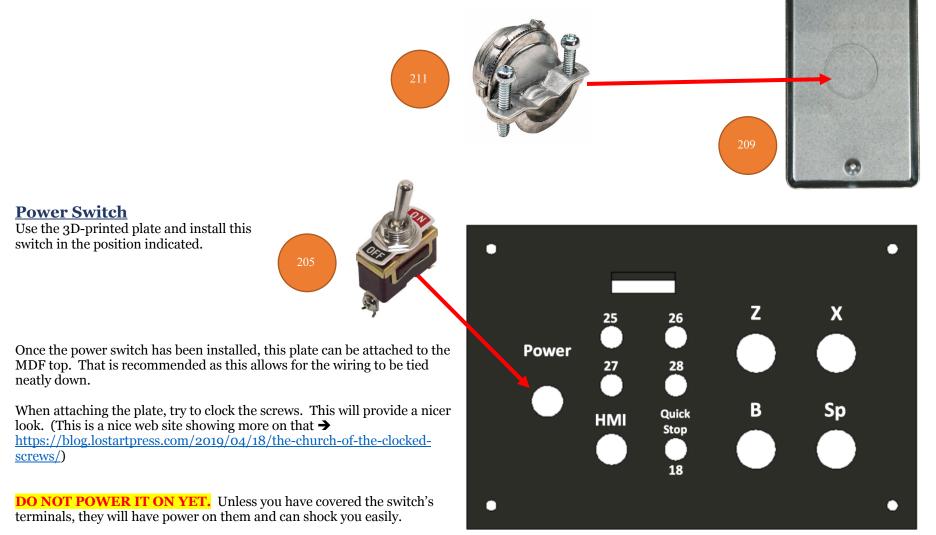


Build Instructions – Control System for Multiple Stepper Motors

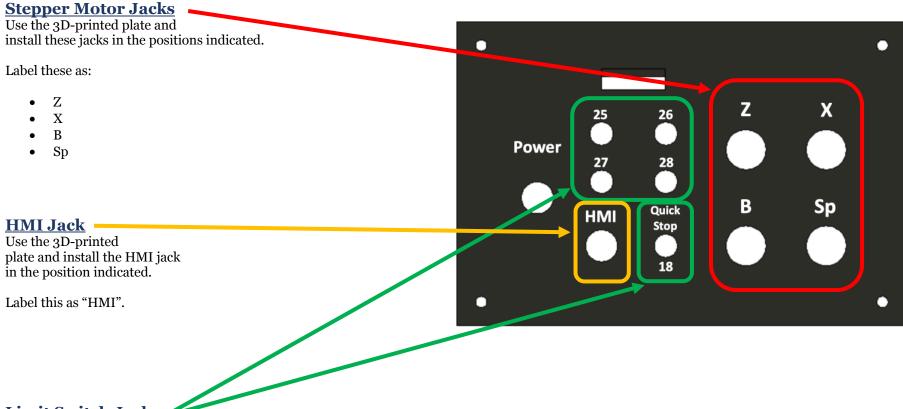
Plates for Connectors

Power Infeed

Use a 1-gang plate with the hole punched out for the cable strain relief. Secure the power cable in place using the 3/8 in. Twin-Screw Cable Clamp Connector. Wait until later to tighten the screws holding the power cable into place.



Build Instructions – Control System for Multiple Stepper Motors

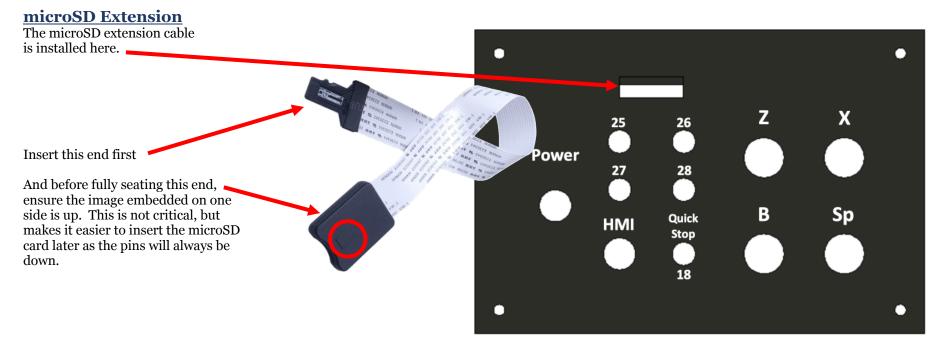


Limit Switch Jacks

Use the 3D-printed plate and install these jacks in the positions indicated.

Label these with the Teensy Pins you are using (18 and 25-28 are shown here).

Build Instructions – Control System for Multiple Stepper Motors



Continue on to Section 2, starting on pg. 34.

Build Instructions – Control System for Multiple Stepper Motors

Section 1, Option 3 – Controls Box Enclosure, v3



- 1. A top and bottom made from ³/₄" MDF,
- 2. Four sides made from ¹/₄" MDF.

The four ¹/₄" thick sides are screwed to the ³/₄" MDF used for the top and bottom.

Replacing the top, and removing the sides reveals the view to the left.

Build Instructions – Control System for Multiple Stepper Motors

Before Assembly The following instructions should be followed before assembling the controls box

Bottom

This is made from ³/₄" MDF.

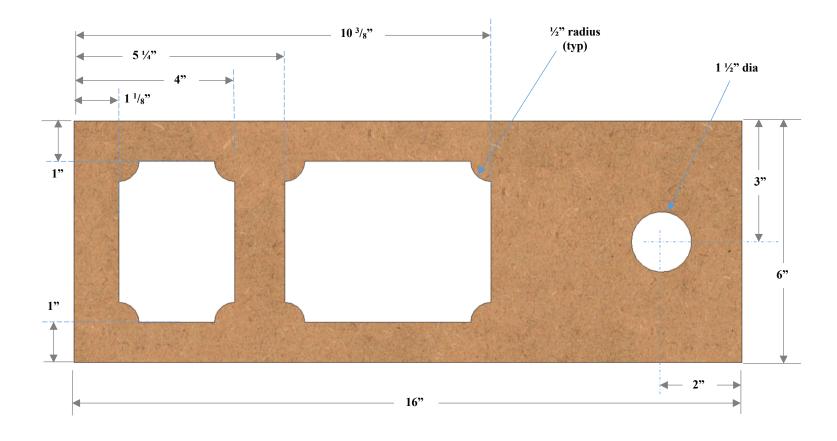


Build Instructions – Control System for Multiple Stepper Motors

<u>Top</u>

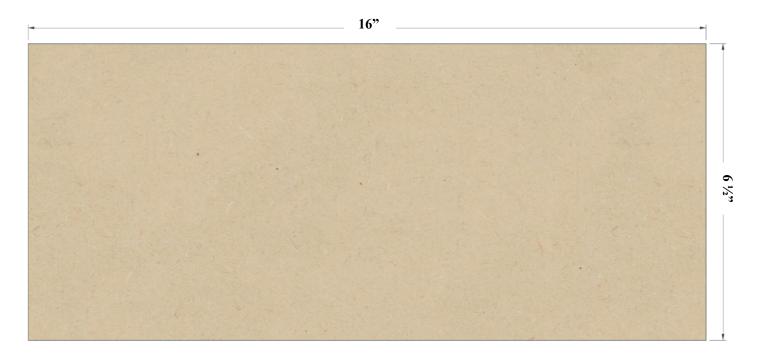
This is made from ³/₄" MDF. This layout is for the version 2 or version 3 plate in the book titled, <u>3D Printed Parts</u>. If you use version 1, modify the layout as necessary.

For the 3D-printed plate's mounting holes, it is best to drill them based on the plate's position after cutting the opening. Do be sure it is properly aligned before drilling the holes.



Build Instructions – Control System for Multiple Stepper Motors

Long Sides (2) There are two of these, and they are made from ¹/4" MDF.



Build Instructions – Control System for Multiple Stepper Motors

Short Sides (2)

There are two of these, and they are made from ¹/4" MDF.



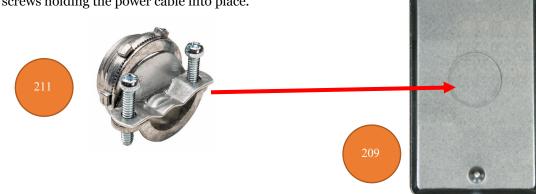
Build Instructions – Control System for Multiple Stepper Motors

Assembly

Plates for Connectors

Power Infeed

Use a 1-gang plate with the hole punched out for the cable strain relief. Secure the power cable in place using the 3/8 in. Twin-Screw Cable Clamp Connector. Wait until later to tighten the screws holding the power cable into place.



Build Instructions – Control System for Multiple Stepper Motors

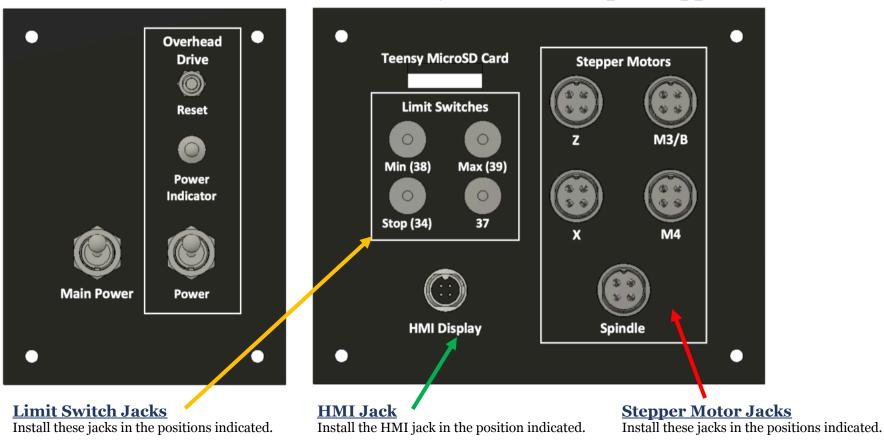


The positions indicated for the overhead drive are a separate option, and detailed in "Instructions for Building Jigs, Fixtures, & Add-Ons".

Once the power switch has been installed, this plate can be attached to the MDF top. That is recommended as this allows for the wiring to be tied neatly down. When attaching the plate, try to clock the screws. This will provide a nicer look. (This is a nice web site showing more on that \rightarrow https://blog.lostartpress.com/2019/04/18/the-church-of-the-clocked-screws/)

DO NOT POWER IT ON YET. Unless you have covered the switch's terminals, they will have power on them and can shock you easily.

Build Instructions – Control System for Multiple Stepper Motors



Build Instructions – Control System for Multiple Stepper Motors

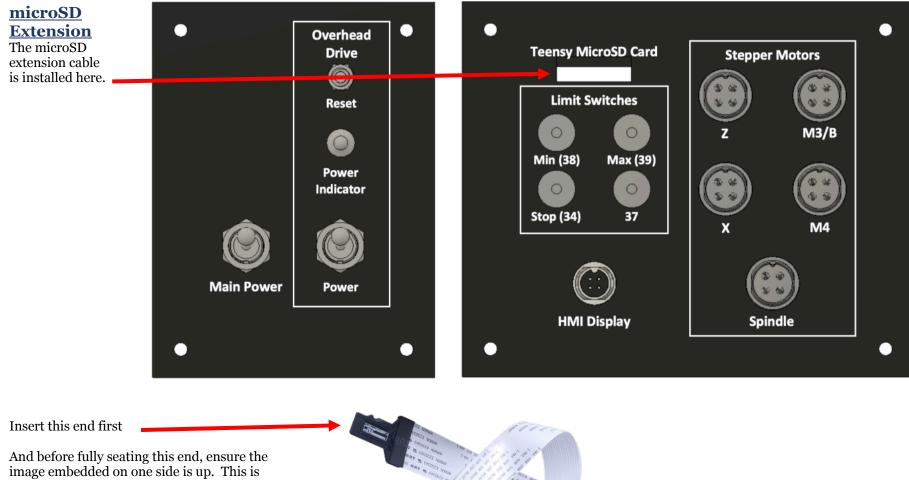


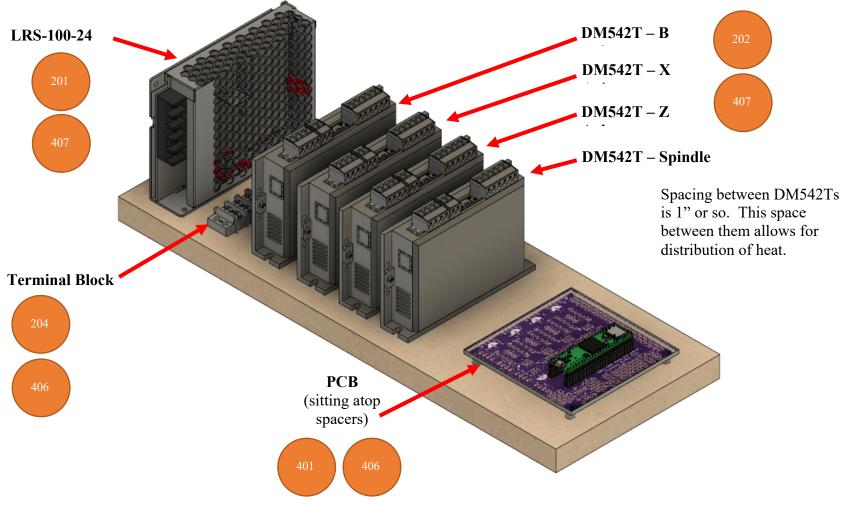
image embedded on one side is up. This is not critical but makes it easier to insert the microSD card later as the pins will always be down.

Build Instructions – Control System for Multiple Stepper Motors

Section 2 – Assembly of the Control Box Electronics

Mounting Electronics to the MDF Base

Mount the electronics to the base piece of the MDF. The PCB is secured to the MDF with the ¹/₄" spacers under the 4 corners to place the board so that there is a ¹/₄" gap below.



Build Instructions – Control System for Multiple Stepper Motors

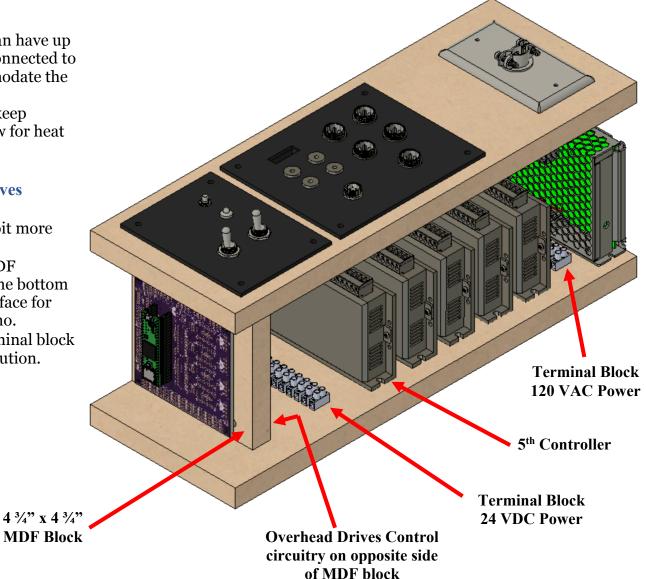
Notes Regarding the V3 Board

• When using this board, you can have up to 5 controllers (DM542Ts) connected to 5 stepper motors. To accommodate the 5th controller, space them out appropriately, but be sure to keep spacing between them to allow for heat to evacuate.

Notes Regarding the Overhead Drives Control

This option requires adding quite a bit more electronics and wiring. Thusly,

- Consider adding a piece of MDF mounted perpendicularly to the bottom board. This will provide a surface for mounting the PCB, the Arduino.
- You should also add a 2nd terminal block for the 120 VAC power distribution.



Build Instructions – Control System for Multiple Stepper Motors

Document Version History

Ver	Date	Comment
4.0	08 Jun 22	• This update accommodates the use of 3D-printed face plate.
3.0	19 Aug 21	• Original document split into 3 parts to allow for different case configurations to be handled easily.
2.1	14 Aug 21	Changed pins used for limit switchesAdded information regarding different Teensy and Nextion displays.
2.0	13 Jun 21	• This document incorporates changes to the way cables are attached to the PCB. It now shows how to use connectors in lieu of soldering the wires directly to the board.
1.4	10 Mar 21	 Reorganized a few steps to follow better flow of work. Added notes on using GX-12/4 connector for Nextion display. Updated instructions for loading software to reference web site. Also added a few minor other tweaks.
1.3	01 Jan 21	 Added item numbers for optional build using a Pololu Tic (this is a separate document). Renamed Document
1.2	15 Dec 20	Added parts to the bill of materialsAdded details on the installation of the 3.5mm phono jacks.
1.1	10 Dec 20	Added details for optional configurations.Added information for attaching the stepper motor to the headstock
1.0.2	07 Dec 20	 Updated p/n for item #204; also updated p/n & qty for item #102. Added note on soldering on 3.5mm jacks first.
1.0.1	05 Dec 20	 Updated commentary about stepper motor needed. Added information about stepper motor mount, pulleys, and belt. Updated drawing dimensions.
1.0	01 Dec 20	Initial document

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Permission is not granted to manufacture these for sale.